

Bernburg
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Köthen



Hochschule Anhalt
Anhalt University of Applied Sciences

emw

Fachbereich
Elektrotechnik, Maschinenbau
und Wirtschaftsingenieurwesen

Projektarbeit

Jian Song

Vorname Nachname

Master Elektro- und Informationstechnik,
4055229

Studiengang, Matrikelnummer

Thema:

Aufbau eines Praktikumsversuches

“Toastersteuerung” mit einem Arduino-Board

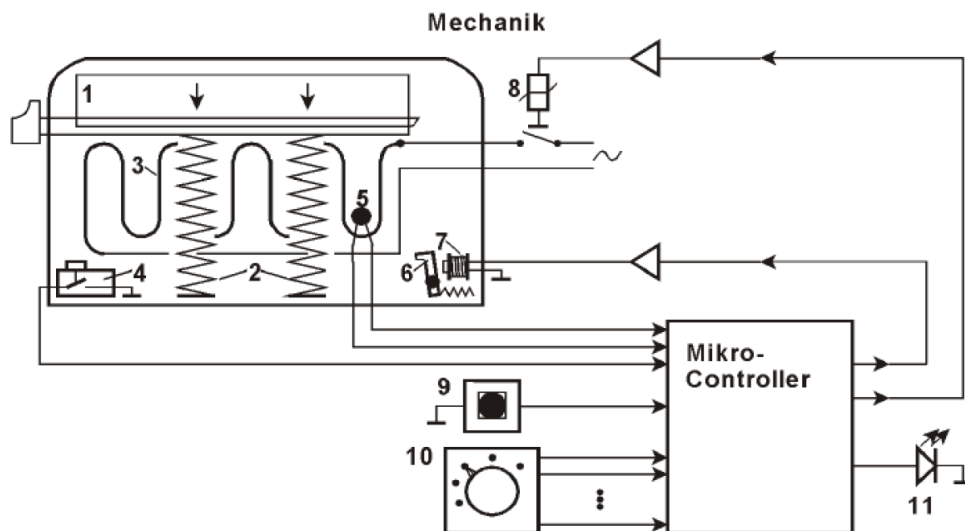
Prof. Dr. Ingo Chmielewski

Betreuer

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1. Schema der Funktionsweise eines Toasters



Die zu steuernde Hardware

- | | | |
|--|------------------------------|-------------------------------------|
| 1 – Korb | 2 – Druckfeder | 3 - Heizwendel |
| 4 – Endlagenkontakt | 5 – Temperatursensor | 6 – Klinge |
| 7 – Auslösemagnet | 8 -Schaltrelais (oder Triac) | 9 – Stoptaste |
| 10 -Dreheschalter zum Einstellen des Bräunungsgrades | | 11 – Kontrollanzeige (Leuchtdiode). |

In dem Fall gibt er kein Endlagenkontakt 4 sondern zwei metallische Blatt. Wenn man Korb drückt, kontaktieren die beiden einander. Mechanische Relay 8 wurde durch ein Solid State Relay ersetzt, damit Relay PWM-Signal erkennen kann. OneWire-Temperatursensor wurde in dem Fall als Rückführung hinzugefügt, damit eine Überhitzung zu Unterbrechung des Systems führt. Arduino-Board wurde mit ein AC/DC-Wandler verbunden und AC/DC-Wandler wurde mit Netzkabel des Toasters verbunden, damit 230V-AC direkt Arduino-Board versorgen kann.

Bevor Programmierung in Arduino-IDE soll man folgende Bibliotheken installieren:

PWM frequency library:

<http://code.google.com/p/arduino-pwm-frequency-library/downloads/list>

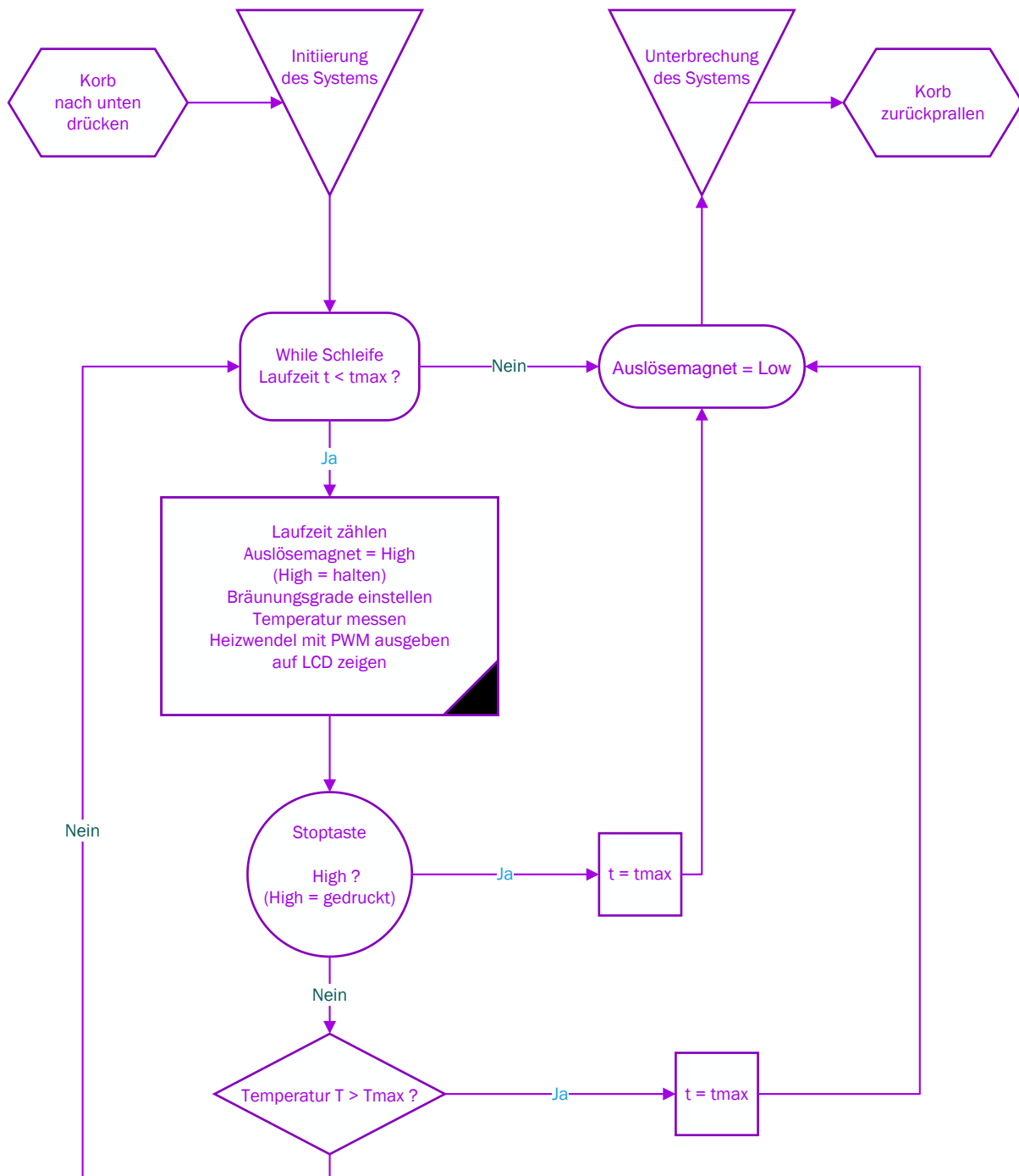
OneWire library:

<https://github.com/PaulStoffregen/OneWire>

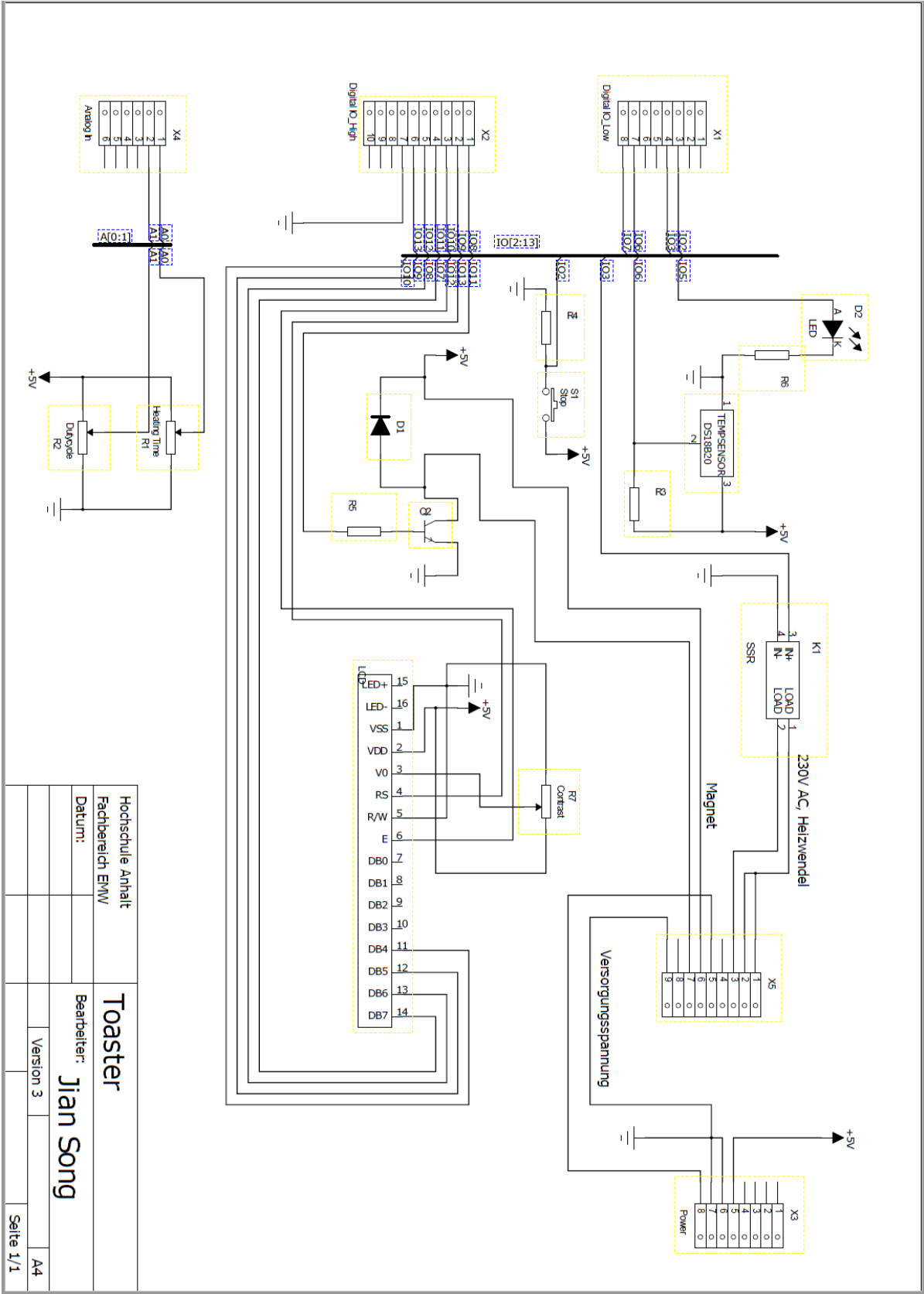
DallasTemperature library:

<https://github.com/milesburton/Arduino-Temperature-Control-Library>

2. Ablauf-Plan des Programms

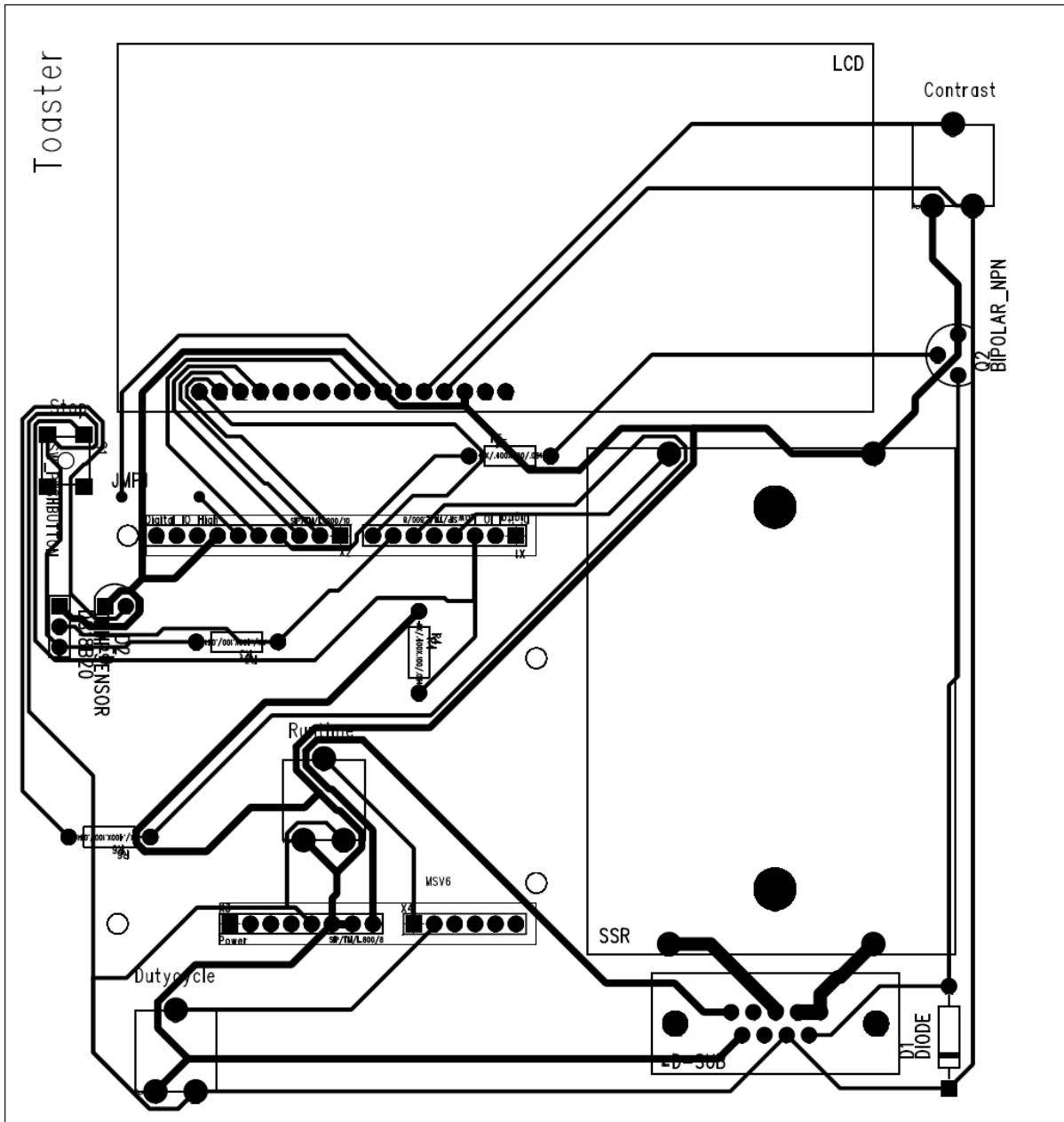


3. Strom Lauf-Plan



Hochschule Anhalt Fachbereich EMW		Toaster	
Datum:		Bearbeiter: Jian Song	
		Version 3	A4
		Seite 1/1	

4. PCB Layout



5. Arduino-Code mit getrennter Funktionen

```
/******
```

```
Toaster Project
```

```
Rev 3
```

```
Jian Song
```

```
Functions:
```

1. Drehschalter
2. Auslösemagnet
3. Temperatursensor
4. Heizwendel
5. Stoptaste
6. LCD
7. Kontrollanzeige

```
*****/
```

```
void Drehschalter() {
```

```
//function for calibration of the heating time
```

```
    int Grades;
```

```
//define the degrees of browning
```

```
    unsigned long tmax = 60000;
```

```
//define the max. heating time
```

```
    Grades = analogRead(0);
```

```
//read the data from pin A0 of analog input
```

```
    if (Grades >= 0 && Grades <= 205) {
```

```
//input range for A0 is from 0 to 1024(because of 10 bit ADC),
```

```
define potentiometer as 5 steps
```

```
        tmax = 10000;
```

```
    }
```

```
    if (Grades > 205 && Grades <= 410) {
```

```
        tmax = 20000;
```

```
    }
```

```
    if (Grades > 410 && Grades <= 615) {
```

```
        tmax = 30000;
```

```
    }
```

```
    if (Grades > 615 && Grades <= 820) {
```

```

        tmax = 40000;
    }
    if (Grades > 820 && Grades <= 1024) {
        tmax = 50000;
    }

}

void Ausloesemagnet() {
//function for magnet trigger

    int Magnet = 11;
//define the magnet
    unsigned long t = 0;
//define the runtime
    pinMode(Magnet, OUTPUT);
//set pin 11 as digital output
    while (t < tmax) {
//run the loop if the runtime is less then tmax
        t = millis();
//returns the number of milliseconds since the Arduino board began
running the current program
        digitalWrite(Magnet, HIGH);
//turn on the magnet
    }
    digitalWrite(Magnet, LOW);
//turn off the magnet, if the loop is broken

}

void Temperatursensor() {
//function for reading temperature in celsius

    #include <OneWire.h>
//use onewire library
    #include <DallasTemperature.h>
//use dallastemperature library

```



```

        int tempsensor = 6;
//define temperature sensor
        double temperature;
//define the temperature
        double Tmax = 50;
//define the max. temperature
        OneWire onewirepin(tempsensor);
//setup a onewire instance to communicate with any onewire devices
        DallasTemperature sensors(&onewirepin);
//pass our oneWire reference to dallas temperature
        sensors.begin();
//start the library up
        sensors.requestTemperatures();
//send the command to get temperatures
        temperature = sensors.getTempCByIndex(0);
//get the temperature from the first sensor only
        if (temperature > Tmax) {
//compare the current temperature and max. temperature. if higher
than max. , set t as tmax, then that while loop condition in
function of ausloesemagnet is not true anymore, so the while loop
will be broken until reset.
                t = tmax;
        }

}

void Heizwendel() {
//function for controlling the heater

        #include <PWM.h>
//use PWM library

        #define PIN_OUTPUT 3
//define pin 3 as output of PWM
        int D;
//set the dutycycle for PWM(8 bit timer can provide a range from 0
to 255 steps for PWM)

```

```

        int32_t frequency = 10;
//set the frequency of PWM in hertz
        InitTimersSafe();
//initialize all timers except for 0, to save time keeping
functions(for UNO timer0 and timer2 are 8 bit, timer1 is 16 bit;
pins 5 and 6: controlled by timer0; pins 9 and 10: controlled by
timer1; pins 11 and 3: controlled by timer2)
        bool success = SetPinFrequencySafe(PIN_OUTPUT, frequency);
//sets the frequency for pin 3
        D = map(analogRead(1), 0, 1023, 0, 255);
//re-maps the range of analog input A1 from 0 - 1023 to 0 - 255
        pwmWrite(PIN_OUTPUT, D);
//use this functions instead of analogWrite on pin 3

}

void Stoptaste() {
//function for the stop button

        int S;
//define the push button as stop button
        S = digitalRead(2);
//read HIGH or LOW digital signal from pin 2
        if (S == HIGH) {
//if the button is pressed, set t as tmax, then that while loop
condition in function of ausloesemagnet is not true anymore, so the
while loop will be broken until reset.
                t = tmax;
        }
}

void LCD() {

        #include <LiquidCrystal.h>
//use LCD library

```

```

    LiquidCrystal lcd(13, 12, 10, 9, 8, 7);
//initialize the library with the numbers of the interface pins
    lcd.begin(16, 2);
//set up the LCD's number of columns and rows
    lcd.setCursor(0, 0);
//set the cursor to column 0, line 0(line 0 is the first row, since
counting begins with 0)
    lcd.print("T=");
//print "Temperature = "
    lcd.print(temperature);
//print temperature in celsius
    lcd.print("`C ");
    lcd.print("t=");
//print "Time = "
    lcd.print(millis()/1000);
//print current runtime in seconds
    lcd.print("s");
    lcd.setCursor(0, 1);
//set the cursor to column 0, line 1
    lcd.print("D=");
//print "Dutycycle = "
    lcd.print((D*100)/255);
//print current dutycycle in percent
    lcd.print("% ");
    lcd.print("tmax=");
//print "max. runtime = "
    lcd.print(tmax/1000);
//print preset of max. runtime in seconds
    lcd.print("s  ");

}

void Kontrollanzeige() {
//shows the status, if PWM is working

    #define LED 5
    analogWrite(LED, D);
//put a LED and resistor between pin 5 and GND
}

```